

HMC4100

MARINE ENGINE CONTROLLER

USER MANUAL



SMARTGEN (ZHENGZHOU) TECHNOLOGY CO., LTD.



F. K. China
 Tel: 0086-371-67988888
 0086-371-67981888
 0086-371-67991553
 0086-371-67992951
 0086-371-67981000 (overseas)
 Fax: 0086-371-67992952
 Web: www.smartgen.com.cn

 www.smartgen.cn
 Email: sales@smartgen.cn

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Table 1 - Version History

Date	Version	Content
2018-09-20	1.0	Original release



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1 OVERVIEW

HMC4100 marine engine controller integrates digitization, intelligentization and network technology which are used for genset automation and monitor control system of single unit to achieve remote controlling for diesel engine, local start/stop, data measure, alarm protection and "three remote" (remote control, remote measuring and remote communication). It fit with 132*64 liquid display, optional Chinese/English languages interface, and it is reliable and easy to use.

The powerful 32-bit ARM processor contained within the module allows for precision parameters measuring, fixed value adjustment, time setting and set value adjusting and etc..Majority parameters can be configured from front panel and can be configured by communication interface via PC. Due to its compact structure, simple connections and high reliability, **HMC4100** can be widely used in marine emergency engines, main propulsion engines, main generator engines and pumping engines.

HMC4100 marine engine controller has an expansion CANBUS port that will be connected to a remote control module or expansion digital output module, LED indicator expansion module and security module.

2 PERFORMANCE AND CHARACTERISTICS

- 32-bit ARM micro-processor, 132*64 liquid display, optional Chinese/English interface, push-button operation;
- Connect with remote monitoring module via CANBUS port to realize remote monitoring and remote start/stop control;
- RPU560A security module can be expanded via CANBUS port;
- > Dozens of engines compatible with J1939 protocol can be monitored via CANBUS port;
- RS485 communication ports enable data transmission as well as remote control, remote measurement and remote communication;
- > Control and protection: remote/local start and stop, alarm protection;
- > Override mode, in which only overspeed and manual emergency shutdown can stop the engine;
- Parameter setting: parameters can be modified and stored into internal FLASH memory and can not be lost even in case of power outage;
- Six sensor inputs for pressure, temperature, fuel level or other sensors; pressure sensor, Flexible sensor2~3 also can be set to (4~20)mA inputs and (0~5)V inputs;
- > Real-time clock, engine total run-time accumulation, display the total start times;
- Built-in speed detection, which can accurately judge crank disconnect status, rated speed running and overspeed status.
- > 99 event logs can be saved circularly and can be inquired on the spot;
- Digital regulation of all parameters instead of analog regulation using conventional potentiometer -



and, therefore, higher reliability and stability;

Modular design, self extinguishing50% ABS+50%PC plastic enclosure and embedded installation way; small size and compact structure with easy mounting.

3 TECHNICAL PARAMETERS

Table 2 – Technical Parameters

Parameter	Details			
Working Voltage	DC8.0V to DC35.0V, uninterrupted power supply.			
Power Consumption	<3W (Standby mode: ≤2W)			
Speed Sensor Voltage	1.0V to 24V (RMS)			
Speed Sensor Frequency	Max 10,000 Hz			
Start Relay Output	5A DC28V			
Programmable Relay Output 1	5A DC28V			
Programmable Relay Output 2~6	1A DC28V			
	3 Fixed resistor type sensors(temperature, oil temperature, and			
Analog Sanaar	flexible sensor 1)			
Analog Sensor	3 sensors can be configured as resistor/current/voltage type (oil			
	pressure, flexible sensor 2, and flexible sensor 3).			
Case Dimension	135 mm x 110 mm <mark>x 4</mark> 4 mm			
Panel Cutout	116mm x 90mm			
Working Conditions	Temperature: (-25~+70) ^o C; Ralative Humidity: (20~93)%RH			
Storage Conditions	Temperature: (-25~+70)°C			
Brotaction Loval	IP65: when water-proof gasket ring inserted between panel and			
	enclosure			
Weight	0.35kg			
51				



4 INFORMATION INTERFACE

Display Screen	Display Content	Description		
After pressing Enter for	Return	After selected controller information, press Enter		
1s, the controller will	Parameter Setting	to enter into controller information interface.		
enter into parameter	Controller Information			
setting and information	Event Log			
selection interface.	USB Enabled			
First Panel	Controller Information	This panel will display software version,		
	Software Version: 1.1	hardware version and controller time.		
	Release Date: 2018-09-20			
	2018.10.15(5)09:30:10	Press 🖤 or 🖤 to scroll screen.		
Second Panel	O:C 1 2 3 4 5 6	This panel will display output port status, and		
		genset status.		
		Press Or Ot to scroll screen.		
	Standby			
Third Panel	l: 1 2 3 4 5 6	This panel will display input port status, and		
	2222	engine status.		
		Press Or O to scroll screen.		
	Standby			

5 OPERATOR INTERFACE

5.1 PUSHBUTTONS DESCRIPTION

Table 4 – Keys Function Description

lcon	Button	Description
0	Stop	Stop running generator in local mode; During stopping process, press this button again to stop generator immediately.
	Start	Start standby genset in local mode.
Ŕ	Alarm Mute	Alarm sound off.
j III	Self-Check	In standby mode, pressing this button can test alarm without rotate speed.
5	Alarm Reset	If alarm occurs, pressing this button will reset it.
Δ	Up	 Screen scroll. Up cursor and increase value in setting menu.
₽	Down	 Screen scroll. Down cursor and decrease value in setting menu.
\$	Set	 Pressing and holding for more than 1 second entry the parameter configuration menu; In settings menu confirms the set value



5.2 CONTROLLER PANEL



Fig.1 - HMC4100 Front Panel Drawing

5.3 START/STOP OPERATION OF REMOTE CONTROL

5.3.1 ILLUSTRATION

Deploy any aux. input port of HMC4100 to remote start input. After the "remote mode" is active, remote start/stop operation can be achieved via remote monitoring module..

5.3.2 REMOTE START SEQUENCE

- When "Remote Start" is active, "Start Delay" timer is initiated (if remote start command is active, unit enters "Preheat" directly);
- "Start Delay" countdown will be displayed on status page of LCD;
- When start delay is over, preheat relay energizes (if configured), "preheat delay XX s" information will be displayed on LCD;
- After the above delay, the "Fuel Relay" is energized, and then one second later, the "Start Relay" is engaged. Genset is cranked for a pre-set time. If genset fails to fire during this cranking attempt then the fuel relay and start relay are disengaged for the pre-set rest period; "Crank Rest Time" begins and waits for the next crank attempt;
- Should this start sequence continue beyond the set number of attempts, the controller will initiate "Fail to Start" alarm, and alarm information will be displayed on the alarm page of LCD;
- In case of successful crank attempt, the "Safety On" timer is activated. As soon as this delay is over, "start idle" is started (if configured);
- After the start idle delay expired, controller will enter into "Warming Up" (if configured);
- When "Warming Up" delay is over, the generator will enter into "Normal Running" status.

5.3.3 REMOTE STOP SEQUENCE

- When the "Remote Stop", the "Stop Delay" is initiated (if remote stop command is active, unit enters "Cooling" directly).
- Once this "stop delay" has expired, "Cooling" starts;



- After "Cooling" completed, the genset enters into "Stop Idle" status (if configured), and idle relay is energized;
- Once "Stop Idle" delay has expired, the "ETS Solenoid Hold" begins. ETS relay is energized while fuel relay is de-energized.
- Once this "ETS Solenoid Hold" has expired, the "Fail to Stop Delay" begins. Complete stop is detected automatically.
- Generator is placed into its standby mode after its complete stop. Otherwise, fail to stop alarm is initiated and the corresponding alarm information is displayed on LCD (If generator is stop successfully after "Fail to Stop" alarm has initiated, it will enter into "Engine Standby" status).

5.4 AUTO MODE START/STOP OPERATION

5.4.1 ILLUSTRATION

Deploy any Aux. input port to auto-mode input. After the "auto mode" is active, Start/Stop operation can be initiated.

5.4.2 AUTO START SEQUENCE

- When "Auto Start" input is active or "Start/ Stop" input is active, "Preheat Delay" will be started;
- Preheat relay outputs, and "preheat delay XX s" information will be displayed on LCD;
- After the above delay, the fuel relay is energised, and then one second later, the start relay is engaged. The genset is cranked for a pre-set time. If the genset fails to fire during this cranking attempt then the fuel relay and start relay are disengaged for the pre-set rest period; "Crank Rest Time" begins and waits for the next crank attempt;
- Should this start sequence continue beyond the set number of attempts, the controller will initiate
 "Fail to Start" alarm, and alarm information will be displayed on the alarm page of LCD;
- In case of successful crank attempt, the "Safety On" timer is activated. As soon as this delay is over, "start idle" delay is initiated (if configured);
- When the "start idle" delay is over, "warming up" will start (if configured).
- When "warming up" delay is over, generator will enter into "Normal Running" status.

5.4.3 AUTO STOP SEPUENCE

- When "Stop Input" is active or "Start/Stop" input open, "Cooling" started;
- Once the "Cooling" delay has expired, the "Stop Idle" delay is initiated (if configured). During "Stop Idle" Delay, idle relay is energized;
- Once the "Stop Idle" delay has expired, "ETS Solenoid Hold" begins. ETS relay is energized while fuel relay is de-energized;
- Once this "ETS Solenoid Hold" has expired, the "Fail to Stop" delay begins. Complete stop is detected automatically.
- Generator is placed into its standby mode after its complete stop. Otherwise, fail to stop alarm is

initiated and the corresponding alarm information is displayed on LCD (If generator is stop successfully after "Fail to Stop" alarm has initiated, it will enter into "Engine Standby" status).

5.5 LOCAL START/STOP OPERATION

5.5.1 ILLUSTRATION

SmartGen

Deploy any aux. input port to local-mode input. After the "local mode" is active, Start/Stop operation will be doable by pressing buttons on the controller.

Uder local-mode, "Idle Output" is unavailable.

5.5.2 LOCAL START SEQUENCE

- Press button to start the gen-set; preheat relay energizes (if configured), "preheat delay XX s" information will be displayed on LCD;
- After the above delay, the "Fuel Relay" is energised, and then one second later, the "Start Relay" is engaged. The genset is cranked for a pre-set time. If the genset fails to fire during this cranking attempt then "ETS Solenoid Hold" will start;
- In case of successful crank attempt, the "Safety On" timer is activated;
- After the "Safety On" delay expired, if the rotate speed, temperature and oil pressure of controller are regular, the generator will enter into "Normal Running" status directly.

5.5.3 LOCAL STOP SEQUENCE

- Press button to enter into "ETS Solenoid Hold". ETS relay is energized while fuel relay is de-energized.
- Once the "ETS Solenoid Hold" has expired, "Fail to Stop Delay" begins. Complete stop is detected automatically.
- Generator is placed into its standby mode after its complete stop. Otherwise, fail to stop alarm is initiated and the corresponding alarm information is displayed on LCD (If generator is stop successfully after "Fail to Stop" alarm has initiated, it will enter into "Engine Standby" status).

System Mode	Local Start	Local Stop	Remote Start Input	Stop Input	Remote Start/Stop Input	Auto Start Input	Remote Module Start	Remote Module Stop
Local	•	•	-	-	-	-	-	-
Remote	-	-	•	•	-	-	•	•
Auto	-	-	-	•	•	•	-	-

Table 5 -	- HMC4100	Start/Stop	Description
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6 ALARMS

6.1 WARNING

Warning alarms does not lead to shutdown and the detailed alarm information will be displayed on LCD.

No.	Туре	Detection Range	Description
			When the controller detects that the engine speed has
	Overeneed		exceeded the pre-set value, it will initiate a warning alarm
1.	Over speed	Always active.	and the corresponding alarm information will be displayed
			on LCD.
			When the controller detects that the engine speed has
2	Lindor chood	From "Warming up"	fallen below the pre-set value, it will initiate a warning
Ζ.	Under speed	to "Cooling" delay	alarm and the corresponding alarm information will be
			displayed on LCD.
			When the controller detects that the engine speed is 0 and
3.	Loss of Speed	From "Start Idle" delay to "Stop Idle"	alarm action select as "Warning", it will initiate a warning
	Signal	delay	alarm and the corresponding alarm information will be
			displayed on LCD.
			Among set crank times, if genset failed to start, it will
		Among set crank	initiate a warning alarm and the corresponding alarm
4.	Failed to start	times, after "Start	information will be displayed on LCD.
		Compeleted"	Note: in local mode, start attempt forced set as 1 time, if
			fails to start, no alarms will occur.
		After "Fail to Stop"	After "fail to stop" delay, if speed signal still can be detected,
5.	Failed to stop	Delay	it will initiate a warning alarm and the corresponding alarm
		Delay	information will be displayed on LCD.
			When the controller detects that charger voltage has fallen
6	Charge Alt Fail	When generator is	below the pre-set value, it will initiate a warning alarm and
0.		normal running	the corresponding alarm information will be displayed on
			LCD.
			When the controller detects that the auxiliary input 1-6
7.	Aux. Input 1-6	User defined	warning signals, it will initiate a warning alarm and the
			corresponding alarm information will be displayed on LCD.
			When the controller detects that the high water
8	High Water	Bigger than set	temperature warning signals, it will initiate a warning alarm
0.	Temperature	speed	and the corresponding alarm information will be displayed
			on LCD.



No.	Туре	Detection Range	Description
9.		Discourthan ant	When the controller detects that the high oil temperature
		Bigger than set	warning signals, it will initiate a warning alarm and the
	remperature	speed	corresponding alarm information will be displayed on LCD.
		Piggor than act	When the controller detects that the low oil pressure warning
10.	Low Oil Pressure	Bigger than set	signals, it will initiate a warning alarm and the corresponding
		speed	alarm information will be displayed on LCD.
	Elovible concor 1.2	Piggor than sot	When the controller detects that the Flexible sensor 1-3
11.	High	spood	warning signals, it will initiate a warning alarm and the
	riigri	speed	corresponding alarm information will be displayed on LCD.
	Elovible concor 1-3	Riggor than sot	When the controller detects that the Flexible sensor 1-3
12.		ыgger than set	warning signals, it will initiate a warning alarm and the
	LOW	speed	corresponding alarm information will be displayed on LCD.
			When the controller detects that the water temperature
12	Water	Always activo	sensor open warning signals, it will initiate a warning alarm
13.	Temperature Open	Always active.	and the corresponding alarm information will be displayed
			on LCD.
		Always active.	When the controller detects that the oil temperature
14	Oil Temperature		sensor <mark>open</mark> warning signals, it will initiate a warning alarm
14.	Open		and the corresponding alarm information will be displayed
			on LCD.
			When the controller detects that the oil pressure sensor
15	Oil Pressure Open	Always active.	open warning signals, it will initiate a warning alarm and
10.	on ressure open		the corresponding alarm information will be displayed on
			LCD.
			When the controller detects that the Flexible sensor 1-3
16	Flexible sensor 1-3		open warning signals, it will initiate a warning alarm and
10.	Open		the corresponding alarm information will be displayed on
			LCD.
			When the controller detects that the supply voltage has
17	Supply Under Volt	Always active	fallen below the pre-set value for more than 20s, it will
		, indye douve.	initiate a warning alarm and the corresponding alarm
			information will be displayed on LCD.
			When the controller detects that the supply voltage has
18	Supply Over Volt	Always active	exceeded the pre-set value, it will initiate a warning alarm
		niways active.	and the corresponding alarm information will be displayed
			on LCD.
19	DOUT 16 Comm.	Always active	When the controller detects DOUT 16 module
19.	Fail	(When DOUT16 is	communication failure, it will initiate a warning alarm and



No.	Туре	Detection Range	Description			
		enabled).	the corresponding alarm information will be displayed on			
			LCD.			
		Always active	When the controller detects HMC4000RM module			
20	HMC4000RM	(When	communication failure, it will initiate a warning alarm and			
20.	Comm. Fail	HMC4000RM is	the corresponding alarm information will be displayed on			
		enabled)	LCD.			
		Always active	When the controller detects RPU560A module			
21	RPU560A Comm.	Always active	communication failure, it will initiate a warning alarm and			
21.	Fail		the corresponding alarm information will be displayed on			
		enableu).	LCD.			
	Fresh Water		When the input port defines this function, the controller will			
22.	Pressure Low	Always active.	initiate a warning alarm and the corresponding alarm			
	Input		information will be displayed on LCD.			
	Fresh Water Lovel		When the input port defines this function, the controller will			
23.		Always active.	initiate a warning alarm and the corresponding alarm			
	Low input		information will be displayed on LCD.			
	Grosso Lovel Low		When the input port defines this function, the controller will			
24.		Always active.	initiate a warning alarm and the corresponding alarm			
	input		information will be displayed on LCD.			
	Fuel Leekage		When the input is active, the controller will initiate a			
25.		Always active.	warning alarm and the corresponding alarm information			
	Input		will be displayed on LCD.			
			When there is an ECU warning, the corresponding alarm			
26	ECILWarning		information will be displayed on LCD; meanwhile, SPN			
20.	ECO wanning	Always active.	and FMI of changing ECU alarm will be displayed.			
			Maximum 5 SPN codes of ECU alarm can be displayed.			
▲	Note: warning type of	aux. input must be act	ive when configured by users.			
	DOUT16 module: expand 16 chanels of discrete output.					
	RPU560A module: expand security module.					





6.2 SHUTDOWN

If the controller detects shutdown alarms, controller will shutdown genset and the detailed alarm information will be displayed on LCD.

No.	Туре	Detection Range	Description
			When the controller detects that emergency stop is active,
1.	Emergency Stop	Always active	it will initiate a warning alarm and the corresponding alarm
			information will be displayed on LCD.
			When the controller detects that the engine speed has
2	Overeped		exceeded the pre-set value, it will initiate a shutdown
Ζ.	Over speed	Always active.	alarm and the corresponding alarm information will be
			displayed on LCD.
			When the controller detects that the auxiliary input 1-6
3.	Aux. Input 1-6	User defined	shutdown signals, it will initiate a shutdown alarm and the
			corresponding alarm information will be displayed on LCD.
			When the controller detects that the high water
1	High Water	Bigger than set	temperature shutdown is active, it will initiate a shutdown
4.	Temperature	speed	alarm and the corresponding alarm information will be
			displayed on LCD.
	High Oil	Bigger than set	When the controller detects that the high oil temperature
5.	Temperature		shutdown is active, it will initiate ashutdown alarm and the
	Temperature	Speed	corresponding alarm information will be displayed on LCD.
		Bigger than set	When the controller detects that the low oil pressure warning
6.	Low Oil Pressure		shutdown is active, it will initiate a shutdown alarm and the
		Speed	corresponding alarm information will be displayed on LCD.
	Elevible sensor 1-3	Bigger than set	When the controller detects that the Flexible sensor 1-3
7.	High	spood	shutdown is active, it will initiate a shutdown alarm and the
	i ligit	speed	corresponding alarm information will be displayed on LCD.
	Flevible sensor 1-3	Bigger than set	When the controller detects that the Flexible sensor 1-3
8.		sneed	shutdown is active, it will initiate a shutdown alarm and the
	2010	speed	corresponding alarm information will be displayed on LCD.
			When there is an ECU shutdown, the corresponding alarm
٩	ECI I Shutdown	Always active	information will be displayed on LCD; meanwhile, SPN
9.		Always active.	and FMI of changing ECU alarm will be displayed.
			Maximum 5 SPN codes of ECU alarm can be displayed.
۵	Note: shutdown type of aux. input must be active when configured by users .		

Table 7 – Shutdown Alarms



7 PARAMETER CONFIGURATION

Hold and press for 1s to enter into parameter setting menu after input the correct password (Default password as 00318). Please contact the manufacturer if forget password or need sensor resistance/current calibration.

Parameter	Range	Default	Remarks
1. Start delay	(1-3600) s	1	The time from remote start signal active to complete start when the controller is in remote mode.
2. Return delay	(1-3600) s	1	The time from remote stop signal active to complete stop when the controller is in remote mode.
3. Preheat delay	(0-3600) s	0	The time of heater plug energized before starter energized.
4. Cranking Time	(3-60) s	8	The every starter energized time.
5. Crank Rest Time	(3-60) s	10	The waiting time before second energizes start when starter failed to start.
6. Safety On Time	(0-3600) s	10	First running time after machine started.
7. Start Idle Time	(0-3600) s	0	Idle time when genset start.
8. Warming Up Time	(0-3600) s	10	Warming up time after genset running up.
9. Cooling Time	(0-3600)s	10	Cooling time before stop.
10. Stop Idle Time	(0-3600) s	0	Stop idle time when stop.
11. ETS Hold Time	(0-3600) s	20	Stop magnet energized time when the genset is to stop.
			Time from idle delay finished to wait stop
12. Wait Stop Time	(0-3600) s	0	when "ETS hold time" is set to 0; time from ETS hold to wait stop when "ETS hold time" isn't set to 0.
13. Start Key Confirm Time	(0.2-5.0) s	0.2	The time from pressing start button to start performance when the controller starts by button-press.
14. Stop Key Confirm Time	(0.2-5.0) s	0.2	The time from pressing stop button to stop performance when the controller stops by button-press.
15. Engine Type	(0-39)	0: Converntional Engine	Factory default: conventional engine (not J1939). Please select related engine type when connect with J1939.
16. SPN Version	(1-3)	1	It is analysis type of SPN alarm.
17. ECU Shutdown Enable	(0-1)	0: Disabled	Shutdown when detect a red lamp alarm after it is enabled.
18. Flywheel Teeth	(1-300)	118	The flywheel teeth installed in genset is used for judgement of separate conditions and detection of rotate speed. See following Installations.

Table 8 – Parameter Configuration Items List



	Parameter	Range	Default	Remarks
19.	Rated Speed	(1-5999)r/min	1500	Provide standard for judgement of over speed, under speed and on load rotate speed.
20.	Start	(1-30)	3	The maximum of start attempts when genset failed to start. When it arrive pre-set value, the controller will send failed to start signal.
21. C	Crank Disconnect ondition	(0-2) 0: Speed 1: Oil Pressure 2: Speed+ OP	0: Speed	The three disconnection conditions of starter and engine, which can be used alone or simultaneously, are used to make starter motor disconnect with engine as soon as possible.
22.	Disconnect OP	(10-1000)kPa	80	Disconnect when Oil Pressure exceeds preset value.
23.	Disconnect Speed	(0-200)%	25%	Set value is percentage of rated rotate speed. When speed exceeds pre-set value, starter will separate.
24. S	Under Speed hutdown	(0-1) 0 Disabled 1 Enabled	0 Disabled	Under speed shut setting.
25.	Set Value	(0-200)%	85%	
26.	Delay	(0-3600) s	3	
27. W	Under Speed /arn	(0-1) 0 Disabled 1 Enabled	0 Disabled	
28.	Set Value	(0-200)%	90%	Under speed warn setting.
29.	Return Value	(0-200)%	92%	
30.	Delay	(0-3600) s	3	
31. S	Over Speed hutdown	(0-1) 0 Disabled 1 Enabled	1 Enabled	Over speed shut setting.
32.	Set Value	(0-200)%	115%	
33.	Delay	(0-3600) s	1	
34.	Over Speed Warn	(0-1) 0 Disabled 1 Enabled	1 Enabled	Over apped were patting
35.	Set Value	(0-200)%	110%	over speed warn setting.
36.	Return Value	(0-200)%	108%	
37.	Delay	(0-3600) s	3	
38.	Speed Lose Delay	(0-3600) s	3	The time from that detecting speed is 0 to confirm action.
39. A	Speed Lose ction	(0-2) 0:Warn 1: Shutdown 2: No Action	1: Shutdown	The action after detecting loss of speed signal.
40.	Charge Alt Fail	(0-60.0)V	16.0	If the voltage of charger falls below the setting limit after engine is normal running, controller



	Parameter	Range	Default	Remarks
				will initiate corresponding alarm.
11	Pat Pated \/alt		24.0	Provide standard for judgement of over
41.	Dai Naleu Voli	(0-00.0) v	24.0	voltage and under voltage.
42.	Power Over Volt	(0-200)%	125%	Set value is percentage of power supply rated
43.	Power Under Volt	(0-200)%	75%	voltage.
44	Heating Up Limit	(0-100)℃	42	Open when temperature of water temperature
			12	sensor is larger than pre-set value.
45.	Heat Down Limit	(0-100) ℃	37	Close when temperature of water
				temperature sensor is less than pre-set value.
46.	Pre-lubricate	(0-1)0		It can circulate prelubricate for genset after
E	nable	Disabled 1	0 Disabled	setting enabled.
		Enabled		
47.	Cyc Gapi Time	(0-7200)min	300	It can set circulate period after circulate
10	Lubri Timo	(0.7200)c	200	The time of each prolubrication
40.		(0.200)s	300 700	Value of reted idle speed of the controller
49. 50		(0-2000)1/11111	1.0	Paley automatic apaced regulation patting
50.	Gain	(0-100)%	10	Note: as rated idle percent (in no working
52	Response	0.25-4.00	0.50	area idle): as rated speed percent (in high
52.	Stability	(0.05-1.60)s	1.0	speed)
54	Device ID	(0.05-1.00)3	1	RS485 Comm Address
54.	Device ID	(0-1)	1	Address.
55	Language Select	0: Chinese	0 [°] Chinese	Language selections
55.		1: English		
56.	Password	(0-65535)	00318	Password of parameter setting.
				If DOUT16 module is needed to expand, this
57.	DOUT16 Enable	(0-1)	0 Disabled	setting enabled is needed.
58.	HMC4000RM			If HMC4000RM module is needed to expand,
E	nable	(0-1)	0 Disabled	this setting enabled is needed.
50	DDU5604 Enchlo	(0, 1)		If RPU560A module is needed to expand, this
59.	RP0560A Enable	(0-1)	0: Disabled	setting enabled is needed.
		(0-1)	0:250kbps	
60.	Baud Rate	0: 250kbps	0. 230kbps	CANBUS port communication Baud rate.
		1: 125kbps		
		(0-1)		When self-check is set as 1, it can test alarm
		0 [°] Self-Check		by connecting with corresponding sensor with
61.	Self-Check Type	Mode 1	0	no rotated speed after self-check is active;
	51	1: Self-Check		when self-check is set as 2, it can test alarm
		Mode 2		with system auto-regulating the sensor after
<u> </u>	Data 9 Time			Self-Check is active;
62.	Date & Time			Date& I ime setting.
62	Watar	See 8.3. Sens	ortunction	
оз. т	vvalei	Noto: Posistor	nco tuno input	Water temperature senser setting
	sistance input)	measuring ran	ne is not	water temperature sensor setting.
(1.03		applicable.	90 10 1101	



	Parameter	Range	Default	Remarks	
		See 8.3. Sensor function			
64. Oil Temp.Sensor		settings			
s	et	Note: Resistance type input		Oil temperature sensor setting.	
(Re	sistance input)	measuring ra	nge is not		
		applicable.			
05		See 8.3. Sen	sor function		
65.	Oil Pressure	settings			
Se	ensor set	Note: Resista	ance type input	Oil pressure sensor setting.	
(Res	sistance/current/volt	measuring ra	nge is not		
IN	put)	applicable.	-		
		See 8.3. Sen	sor function		
		settings			
66. (5	Aux. sensor 1 Set	Note: Resista	ance type input	Flexible sensor1 setting.	
(Res	sistance input)	measuring ra	nge is not		
		applicable.	0		
		See 8.3. Sen	sor function		
67.	Aux. sensor 2 Set	settings			
(Res	sistance/current/volt	Note: Resista	ance type input	Flexible sensor2 setting.	
ìn	put)	measuring ra	nae is not		
		applicable.			
		See 8.3. Sensor function			
68.	Aux. sensor 3 Set	settings			
(Res	sistance/current/volt	Note: Resistance type input		Flexible sensor3 setting.	
in	out)	measuring range is not			
		applicable.			
			25: Emergency		
69.	Input 1 Set	(0-50)	Shutdown	See table 8.1.2.	
70.	Active type	(0-1)	0: Close Activate	Set up input port active of close or open.	
71.	Input 2 Set	(0-50)	18: Local Mode IN	See table 8.1.2.	
72.	Active type	(0-1)	0: Close Activate	Set up input port active of close or open.	
			19: Remote Mode		
73.	Input 3 Set	(0-50)	IN	See table 8.1.2.	
74.	Active type	(0-1)	0: Close Activate	Set up input port active of close or open.	
75.	Input 4 Set	(0-50)	0: Not Used	See table 8.1.2.	
76.	Active type	(0-1)	0: Close Activate	Set up input port active of close or open.	
77.	Input 5 Set	(0-50)	0: Not Used	See table 8.1.2.	
78.	Active type	(0-1)	0: Close Activate	Set up input port active of close or open.	
79	Input 6 Set	(0-50)	0. Not Used	See table 8.1.2	
80	Active type	(0-1)	0: Close Activate	Set up input port active of close or open	
81	Output 1 Set	(0-100)	0: Not Used	See table 8.2.2	
01.			0. Not 03cu	Set up output port be always open or always	
82.	Active type	(0-1)	0: Open	closo	
02		(0.100)	0: Not Llood	Soo table 8.2.2	
03.	Oulpul 2 Sel	(0-100)		Set up output port he always apar or always	
84.	Active type	(0-1)	0: Open	loss output	
05	Outrast 0 and	(0.400)			
85.	Output 3 set	(0-100)	U: Not Used	See table 8.2.2.	



	Parameter	Range	Default	Remarks
86.	Active type	(0-1)	0: Open	Set up output port be always open or always close output.
87.	Output 4 set	(0-100)	0: Not Used	See table 8.2.2.
88.	Active type	(0-1)	0: Open	Set up output port be always open or always close output.
89.	Output 5 set	(0-100)	0: Not Used	See table 8.2.2.
90.	Active type	(0-1)	0: Open	Set up output port be always open or always close output.
91.	Output 6 set	(0-100)	0: Not Used	See table 8.2.2.
92.	Active type	(0-1)	0: Open	Set up output port be always open or always close output.

8 INPUT/OUTPUT PORTS CONFIGURATION

8.1 AUXILIARY INPUTS 1~6 FUNCTIONAL CONFIGURATION

8.1.1 DIGITAL INPUT PORT CONFIGURATION

Table – 9 Digital Input Port Definitions

No.	Settings	Contents	Description	
1	Feature Set	(0- 50)	See 8.1.2 Input Port Functions	
2	Active type	(0-1)	0: Close Activate 1: Open Activate	
2	Activo Pongo	(0.3)	0: After Safe 1: After Start	
5	Active Range	(0-3)	2: Always 3: Never	
4	Action	(0-2)	0: Warn 1: Shutdown 2: Indication	
5	Input Delay	(0-20.0)s		
6	Displayed string	User-defined input port names	20 English symbols or 10 Chinese characters	
S				



8.1.2 INPUT PORTS FUNCTIONS

	Table 10 –	Input	Port I	Functional	Definition
--	------------	-------	--------	------------	------------

No.	Function	Description
0.	Not used	Not used
1.	Custom	Users configured input port settings
2.	Alarm Mute	Can prohibit "Audible Alarm" output when it is active.
3.	Reset Alarm	Can reset all alarms when input is active.
4.	Pre-Lubricate	If output is set as pre-lubrication output, the relay disconnects after the set pre-lubrication delay.
5.	Reserved	
6.	Panel Lock	All buttons in panel are inactive except $igta$ and $igta$.
7.	Quick Start	Cranking will start directly (without preheating) when the input is active.
8.	Remote Start/Stop	Automatically starts the generator in remote mode; the generator will shut down when this input is deactivated. Note: only one method can be chose between remote start/stop input, and remote start input and remote stop input.
9.	AUTO Mode IN	When the input is active, enter into auto mode, the local mode and remote mode is inactive and start/stop can only be achieved via input port.
10.	Turning Chain	Start inhibition when the input is active.
11.	Fuel Leakage Input	When the input active, alarm initiate if fuel leak occurs.
12.	Water Press Low	Connect to digital input of sensor.
13.	Water Level Low	Connect to digital input of sensor.
14.	Oil Level Low	Connect to digital input of sensor.
15.	Water Temp. High IN	Connect to digital input of sensor.
16.	Oil Temp. High IN	Connect to digital input of sensor.
17.	Oil Pressure Low IN	Connect to digital input of sensor.
18.	Local Mode IN	The genset is in local mode when active.
19.	Remote Mode IN	The genset is in remote mode when active.
20.	Remote Start Input	When remote start input is active in Remote Control Mode, controller initiate start command.
21.	Stop Input	When stop input is active in Remote Control Mode or Auto Mode, controller initiate stop command.
22.	Auto Start Input	When auto start input is active in Auto Mode, controller initiate start command.
23.	Override Mode	When over ride mode input is active, only over speed stop and emergency stop are available.
24.	Local/Remote Mode	Inactive stands for local mode, and active stands for remote mode.
25.	Emergency Shutdown	After it is active, controller will shut down the genset immediately and initiate related alarms.
26~50	Reserved	

Note: The name of the input ports 1~6 only can be configured via PC software.



8.2 OUTPUTS PORTS DEFINITION

8.2.1 DIGITAL OUTPUT DEFINITION CONTENTS

No.	Items	Contents	Note
1	Output Function Configuration	(0-100)	
2	Effective ways	0 Open 1 Close	
3	Effective duration	Bit1: Standby Bit2: Pre-heat Bit3: Fuel On Bit4: Crank Bit5: Crank Rest Bit6: Safety On Bit7: Start Idle Bit8: Warm Up Bit9: Wait For Load Bit10: Working Order Bit11: Cooling Bit12: Stop Idle Bit13: ETS Hold Bit14: Wait For Stop Bit15: Stop Failure	
5	Output Delay	(0-100.0)s	
6	Output Time	(0- <mark>3600</mark>)s	

8.2.2 OUTPUT PORT 1-12 FUNCTIONS DEFINITION

Table 12 – Output Port 1-6 Functional Defination

No.	Items	Description
0.	Not Used	Not used
1.	Custom	
		Action when over speed shutdown and emergence stop. It
2.	Air Flap	also can close the air inflow to stop the engine as soon as
		possible.
		Action when warning, shutdown alarms occur. Can be
3.	Audible alarm	connected annunciator externally. When "alarm mute"
		configurable input port is active, it is inhibit to output.
1	Crank Polov	Action when genset is starting and disconnect when crank
4.		success.
Б	Fuel Output	Action when genset is starting and disconnect when stop is
5.		completed.
6.	ETS Hold	Action period: ETS hold delay.
7.	Reserved	
8.	Reserved	
0	Loss of Spood	After safety on delay, the controller active when the engine
9.		speed is 0.



No.	Items	Description	
10		The controller output when the engine is in standby mode	
10.	Pre-iudricate	(user-defined output delay) if pre-lubrication input is active.	
11.	Override Output	The controller output when it is in Override mode.	
10	Boody Co(1)	The controller output when it is in standby mode and no open	
12.	Ready Go(1)	circuit alarms occur.	
10	Heater Cantrol	It is controlled by heating temperature sensor's limited	
13.	Heater Control	threshold.	
		Action from "crank delay" to "start idle delay" and from "stop	
14.	Idle Control	idle delay" to "wait for stop delay". When in local mode, idle	
		control is unavailable.	
15	Common Alarm	Action when genset common warning, common shutdown	
15.		alarms occur.	
16.	Common Shutdown	Action when common shutdown alarms occur.	
17.	Common Warn	Action when common warning alarms occur.	
18.	Input 1 Active	Action when digital input port 1 is active.	
19.	Input 2 Active	Action when digital input port 2 is active.	
20.	Input 3 Active	Action when digital input port 3 is active.	
21.	Input 4 Active	Action when digital input port 4 is active.	
22.	Input 5 Active	Action when digital input port 5 is active.	
23.	Input 6 Active	Action when digital input port 6 is active.	
24	Crank Success	It is output when the engine speed reaches requirements of	
24.		disconnecting with start motor.	
25	Normal Rupping	The gen-set is normal running when the speed reaches rated	
20.	Normai Kunning	requirements.	
26.	Remote Mode Output	The controller output in remote control mode.	
27.	Local Mode Output	The controller output in local mode.	
28.	Ready Go(2)	Output when there is no shutdown alarm.	
29	DOUT16 Com Fail	Action when the controller detects communication failure with	
20.		DOUT16. (3s overtime)	
30.	Shutdown Output	The controller output when it is shutdown mode.	
31	Power Under Volt	Action when the controller detects that the power voltage has	
01.		fallen below the set value.	
32	Power Over Volt	Action when the controller detects that the power voltage has	
02.		exceeded the set value.	
33.	Under Speed Warn	Action when under speed warning alarm occurs.	
34.	Under Speed Shutdown	Action when under speed shutdown alarm occurs.	
35.	Over Speed Warn	Action when over speed warning alarm occurs.	
36.	Over Speed Shutdown	Action when over speed shutdown alarm occurs.	
37.	Emergency Stop	Action when emergency stop alarm occurs.	
38.	Charge Alt Fail	Action when charge failure warning alarm occurs.	
39.	Failed To Start	Action when failed start alarm occurs.	
40.	Failed To Stop	Action when failed stop alarm occurs.	
41.	Reserved		



No.	Items	Description		
42.	Water Temp. Open	Action when water temperature sensor is open circuit.		
43.	Water Temp. High Warn	Action when high water temperature sensor warning alarm.		
44.	Water Temp. High Stop	Action when high water temperature sensor shutdown alarm.		
45.	Oil Temperature Open	Action when oil temperature sensor is open circuit.		
46.	Oil Temperature High Warn	Action when high oil temperature sensor warning alarm.		
47.	Oil Temperature High Stop	Action when high oil temperature sensor shutdown alarm.		
48.	Oil Pressure Open	Action when oil pressure sensor is open circuit.		
49.	Oil Pressure Low Warn	Action when low oil pressure sensor warning alarm.		
50.	Oil Pressure Low Stop	Action when low oil pressure sensor shutdown alarm.		
51.	Sensor 1 Open Warn	Action when Flexible sensor 1 is open circuit.		
52.	Sensor 1 Warn	Action when Flexible sensor 1 warning alarm.		
53.	Sensor 1 Shutdown	Action when Flexible sensor 1 shutdown alarm.		
54.	Sensor 2 Open Warn	Action when Flexible sensor 2 is open circuit.		
55.	Sensor 2 Warn	Action when Flexible sensor 2 warning alarm.		
56.	Sensor 2 Shutdown	Action when Flexible sensor 2 shutdown alarm.		
57.	Reserved			
50	BBUE60A Comm. Foult	Action when the controller detects communication failure with		
50.	RF0300A Comm. Fault	RPU560A safeguard module. (3s overtime)		
59.	RPU560A Power1 Fault	Security module output when 1 way power fault.		
60.	RPU560A Power2 Fault	Security module output when 2 way power fault.		
		When the controller is in idle mode and speed doesn't arrive at		
		rated idle, it output when speed is rising and open		
		automatically when speed arrives at rated idle.		
61.	Rise Speed	When the controller is running up and speed doesn't arrive at		
		rated rotate speed, it output when speed is rising and open		
		automatically when speed arrives at rated rotate speed.		
		Note: Active only when controller is in remote/auto mode.		
		When the controller is in idle mode and speed exceeds rated		
		idle, it output when speed is dropping and open automatically		
		when speed arrives at rated idle.		
62.	Drop Speed	When the controller is running up and speed exceeds at rated		
		rotate speed, it output when speed is dropping and open		
		automatically when speed arrives at rated rotate speed.		
		Note: Active only when controller is in remote/auto mode.		
63.	Sensor 3 Open warn	Action when Flexible sensor 3 is open circuit.		
64.	Sensor 3 Warn	Action when Flexible sensor 3 warning alarm.		
65.	Sensor 3 Shutdown	Action when Flexible sensor 3 shutdown alarm.		
66.	Fuel Leakage Alarm	Output when this alarm is active.		
67.	Reserved			
08. CC				
69.		Output while lamp testing.		
/0~	Reserved			
100				



8.3 SENSOR FUNCTIONAL CONFIGURATION

8.3.1 SENSOR CONFIGURATION

No.	Settings	Contents	Remarks
		(0-3)	Types such as water temperature
		0: Not Used	sensor, oil temperature sensor, and oil
1.	Sensor type	1: Pressure	pressure sensor are not optional and
		2: Temperature	configuration is fixed temperature or
		3: Level	pressure.
2.	Curve Type	Curve types list	See 8.3.2/8.3.3/8.3.4 curve lists
2	Alarm Speed	(0.200)%	Alarm and test when the engine speed
5.	Alaini Speed	(0-200) /8	has exceeded the set value.
			Active when current of sensor is
			between (4~20)mA. Corresponding
4.	Sensor Range	(0-6000)	unit of pressure sensor is kPa;
			Corresponding unit of level sensor
			is %.
			The units displayed on LCD. After
5	Display Inits	Temperature 0: °C 1: °F	selection of units, the displayed data
5.	Display Onits	Pressure 0: kPa 1: bar 2: Psi	will automatically convert according to
			units.
6	Sensor High Shutdown	(0-1)	
0.	Consol High Chataown	0: Enable 1: Disable	
7.	Set Value	(0-6000)	
8.	Delay	(0-3600)s	
q	Sensor Low Shutdown	(0-1)	
J.		0: Enable 1: Disable	
10.	Set Value	(0-4000)	
11.	Delay	(0-3600)s	
12	Sensor High Warn Enable	(0-1)	
12.		0: Enable 1: Disable	
13.	Set Value	(0-6000)	
14.	Return Value	(0-6000)	
15.	Delay	(0-3600)s	
16	Sensor Low Warn Enable	(0-1)	
10.		0: Enable 1: Disable	
17.	Set Value	(0-4000)	
18.	Return Value	(0-4000)	
19.	Delay	(0-3600)s	
20.	First point X (Resistance)	Resistance type (not PT100)	Sensor curve is usor defined
21	Second point X	Posistanco tuno (not PT100)	
<u> </u>	(Resistance)		
22.	Third point X (Resistance)	Resistance type (not PT100)	

Table 13 – Sensors Configuration



No.	Settings	Contents	Remarks
23.	Fourth point X	Registered type (not PT100)	
	(Resistance)	Resistance type (not PT 100)	
24.	Fifth point X (Resistance)	Resistance type (not PT100)	
25.	Sixth point X (Resistance)	Resistance type (not PT100)	
26	Seventh point X	Begisteneg type (pot DT100)	
20.	(Resistance)	Resistance type (not PTTOO)	
27	Eighth point X	Begistened type (not DT100)	
21.	(Resistance)	Resistance type (not PTTOO)	
28.	First point Y (Value)	Resistance type (not PT100)	
29.	Second point Y (Value)	Resistance type (not PT100)	
30.	Third point Y (Value)	Resistance type (not PT100)	
31.	Fourth point Y (Value)	Resistance type (not PT100)	
32.	Fifth point Y (Value)	Resistance type (not PT100)	
33.	Sixth point Y (Value)	Resistance type (not PT100)	
34.	Seventh point Y (Value)	Resistance type (not PT100)	
35.	Eighth point Y (Value)	Resistance type (not PT100)	
36.	User-defined string	User-defined sensor names	Only can be set via upper computer software.

8.3.2 TEMPERATURE CURVES

Table 14 – Temperature Curve List

No.	Contents	Remarks
0	Not Used	
1	PT100	
2	Custom Res Curve	
3	VDO	
4	CURTIS	
5	VOLVO-EC	
6	DATCON	The input range of user defined registeres is between
7	SGX	0.10000 The factory defaulte of water temperature concern
8	SGD	and oil temporature sensor are PT100 sensors
9	SGH	and on temperature sensor are F1100 sensors.
10	Reserved	
11	Cu50	
12	Reserved	
13	Reserved	
14	Reserved	
15	Reserved	

Δ Note: PT100 Resistance type temperature sensor division value is set as 0.385 (0.385 Ω corresponds to 1 °C).



8.3.3 PRESSURE CURVES LIST

No.	Contents	Remarks
0	Not Used	
1	4~20mA	
2	Custom Res Curve	
3	VDO 10bar	
4	CURTIS	
5	Voltage (0.5V-4.5V)	
6	DATCON 10Bar	The input represent lies defined resistance is between
7	SGX	The input range of User-defined resistance is between
8	SGD	(4.20) m A senser
9	SGH	(4-20)IIIA SEISOI.
10	Custom Voltage Curve	
11	Reserved	
12	Reserved	
13	Reserved	
14	Reserved	
15	Reserved	
	· · · · · · · · · · · · · · · · · · ·	

Table 15 – Pressure Curves List

A Note: There is no need to set curve type but range if the pressure sensor is current type.

8.3.4 FUEL LEVEL CURVES

Table 16 – Fuel Level Curves List

No.	Contents	Remarks
0	Not Used	
1	(4~20)mA	
2	Custom Res Curve	
3	SGD	
4	SGH	
5	Reserved	
6	Reserved	The default of LINC 4400 concer time depends have fuel
7	Reserved	Ine default of HMC4100 sensor type doesn't have fuel
8	Reserved	use if need to
9	Reserved	
10	Reserved	
11	Reserved	
12	Reserved	
13	Reserved	
14	Reserved	
15	Reserved	

A Note: There is no need to set curve type but range if the pressure sensor is current type.



9 PARAMETER SETTING

9.1 MATTERS NEED ATTENTION

Press the button for 1 second after start the controller, and then enter into parameter setting menu, which is need to input correct password. The default password is 00318.

Please contact with manufacturer when forgets the password or need to calibrate the resistance/current/voltage value.

- Please modify the controller internal parameters in standby mode(such as starting successfully condition selections, auxiliary inputs, output port configuration, time delay, etc), otherwise the alarm stop or other abnormal phenomena may occur.
- High sensor alarm threshold value must be bigger than the low alarm threshold, otherwise they will both alarm simultaneously.
- Over speed threshold value must be bigger than under speed threshold, otherwise there will be either overspeed or underspeed simultaneously.
- When setting the condition of successful start, the start speed threshold value is supposed to be set lower as possible for quick disconnection of starter.
- Auxiliary input port 1-6 cannot be set to the same project, otherwise correct function cannot arrive.
 However, Auxiliary output port 1-6 can be set to same project.

9.2 SENSOR SETTINGS CLARIFICATION

- When reselect the sensors, the standard value of the selected sensor will be selected. If tempertuare sensor default is set to PT100 (120°C resistance), sensor curve will be the curve of PT100. If it is set to SGD (120°C resistance), sensor curve will be the curve of SGD.
- If standard sensor curve is mismatching with sensor in using, "User-defined sensor" could be chosen, then input user-defined sensor curve.
- When inputting sensor curve, X (resistance) must be input in accordance with the order of growing up, otherwise mistakes will occur.
- Can set ordinate of front several points or last several points to the same. As shown in below:



Fig.2 – Sensor Curves Set

|--|

	N/m ² Pa	kgf/cm ²	bar	psi
1Pa	1	1.02×10^{-5}	$1 x 10^{-5}$	$1.45 \text{x} 10^{-4}$
1kgf/cm ²	9.8x10 ⁴	1	0.98	14.2
1bar	1x10 ⁵	1.02	1	14.5
1psi	6.89x10 ³	7.03x10 ⁻²	6.89×10^{-2}	1



10 BACK PANEL



Fig.3 – HMC4100 Controller Panel

Table 18 - Description of Termina	al Connection
-----------------------------------	---------------

No.	Function	Cable Size	Description	
1.	В-	1.5mm ²	Connected with negative of starter battery.	
2.	B+	1.5mm ²	Connected with positive of starter ba	ttery.
3.	COM1	1.5mm ²		
4.	CRANK	1.5mm ²	Connect to COM1 relay output, rated	5A DC28V
5.	Aux. Output 1(5A)	1.5mm ²		
6.	COM 2	1.0mm ²		
7.	Aux. Output 2(1A)	1.0mm ²	Connect to COM2 relay output,	
8.	Aux. Output 3(1A)	1.0mm ²	rated 1A DC28V	
9.	Aux. Output 4(1A)	1.0mm ²		ltomo oco
10.	Aux Output $E(1A)$	1.0mm ²	Relay normally open volt free	toble 12
11.		1.0mm ²	contact, rated 1A DC28V	
12.		1.0mm ²	Normally open output, rated 1A	
13.	Aux. Output 6(1A)	1.0mm ²	Normally close output, rated 1 A	
14.		1.0mm ²	Relay common point	
15.	ECU CAN H	0.5mm ²	120Ω impedance shielding wire is	
16.	ECU CAN L	0.5mm ²	recommended with one end grounded.	
17.	RS485 A(+)	0.5mm ²	Peremeters can be configured voi PC coffuers	
18.	RS485 B(-)	0.5mm ²	- Parameters can be conligured val PC software	
19.	Aux. Input 1	0.5mm ²	Ground is active (B-)	ltomo ooc
20.	Aux. Input 2	0.5 mm ²	Ground is active (B-)	table 10
21.	Aux. Input 3	0.5 mm ²	Ground is active (B-)	



No.	Function	Cable Size	Description	
22.	Aux. Input 4	0.5 mm ²	Ground is active (B-)	
23.	Aux. Input 5	0.5 mm ²	Ground is active (B-)	
24.	Aux. Input 6	0.5 mm ²	Ground is active (B-)	
25		1.0mm ²	Connect to charger D+(W/L); if witho	ut this
25.	Chager (D+)	1.0mm	terminal, please hang it in the air.	
26.	Aux. Input COM	0.5 mm ²	Internal has been connected to B-	
27.	W/L	0.5 mm ²		
28.	MP2 (connect with B-)	0.5mm ²	Connect to speed sensor of engine, a	and
29.	MP1	0.5mm ²	shielding wire is recommended.	
20	Temperature Sensor	1.0mm ²	Connect to temperature	
30.	Temperature Sensor		sensor(resistor type)	
24		1.0mm ²	Connect to pressure	
51.	On pressure Sensor		sensor(resistor/current/voltage type)	
32.	Oil Temperature Sensor	1.0mm ²	User configured (resistor type) Items s	
33.	Flexible Sensor 1	1.0mm ²	User configured (resistor type) table	
34	Elevible Sensor 2	1.0mm ²	User configured	
54.		1.000	(resistor/current/voltage type)	
25	Elovible Sensor 2	1.0mm ²	User configured	
- 55.		1.01111	(resistor/current/voltage type)	
36.	DC5V	1.0mm ²	Provide power for voltage type sense	or.
37	Sensor COM(B-)	1.0mm ²	Sensor common port; internal of con	troller has
57.		1.01111	been connect with B	
			Achieving software upgrading.	
		1	Pressing "Set" button to enter into menu	
			selection screen. If select "USB Communication	
	USB		Enabled", parameters can be configu	red by PC
			software via USB port connection. Ar	nd then
			press "Set" button again to exit.	
			Note: CANBUS is inactive while USE	3
			communicaiton.	

Note: It is strictly prohibited to take out start battery when the engine is running. Failure to do so can create excessive DC input voltage and result in damage of destruction of equipment!



11 COMMUNICATION AND CONNECTION

11.1 RS485 COMMUNICATION

HMC4100 genset controller has RS485 port which allows the controller to connect to open-type LAN. RS485 applies ModBus communication protocol with the help of PC or DAS (Data Acquisition Systems) operational software provides easy to use marine engine monitoring system management scheme and enables remote control, remote measurement and remote communication.

11.2 CANBUS (J1939) BUS COMMUNICATION

Various expansion modules can be connected to the controller via CANBUS (J1939) port:

- DOUT16 Digital output module: The module connects to the main controller via CANBUS port.
 Main controller transfers the output condition data of digital output module to module to handle via
 CANBUS. All parameters of digital output port can be configured via main controller.
- HMC4000RM Remote control module: Remote control module can achieve remote control operations such as starting engine, stopping engine, etc. All kinds of parameters and records of the engine real-time display on remote controller.
- RPU560A Security module: The module connects to the main controller via CANBUS port. Its input function, output function and overspeed alarm threshold are user-set.

▲ Note: Remote control module can only be used in remote mode of the engine; in local mode remote control module only can check parameters and records but not control the engine.

11.3 CONTROLLER AND ENGINES CONNECTION (EXPANSION CANBUS)

A large number of ECU engines can be connected to the CANBUS (ECU) port of the controller. Besides, at the same time users can connect expansion module which makes it convenient and suitable for different working environments.

11.3.1 CUMMINS ISB/ISBE

Terminals of controller	Connector B	Remarks
Fuel relay output	39	
Start relay output	-	Connect to starter coil directly
Auxiliary output port 1	Expand 30A relay, battery voltage of terminal 01,07,12,13 are supplied by relay.	ECU power; set auxiliary output 1 as "ECU power".

Table 19 – Fuel Start Wiring Connection



Table 20 – 9-Pin Connector Wiring Connection

Terminals of controller	9 pin connector		Rei	marks		
CAN(H) (ECU)	SAE J1939 signal	Impedance	120Ω	connecting	line	is
		recommended.				
CAN(L) (ECU)	SAE J1939 return	Impedance	120Ω	connecting	line	is
		recommende	ed.			

Engine type: Cummins ISB

11.3.2 CUMMINS QSL9

Compatible with CM850 engine controller module.

Table 21 - Fuel Start Wiring Connection

Terminals of controller	50 pin connector	Remark
Fuel relay output	39	
Start relay output	-	Connect to starter coil directly.

Table 22 – 9-Pin Connector Wiring Connection

Terminals of controller	9 pin connector	Remark
CAN(H) (FCU)	SAE J1939 signal-C	Impedance 120Ω connecting line is
		recommended.
	SAE J1939 return-D	Impedance 120Ω connecting line is
		recommended.

Engine type: Cummins-CM850

11.3.3 CUMMINS QSM11

Compatible with CM750 engine controller module. Engine types: QSM11 G1, QSM11 G2

Table 23 - Fuel Start Wiring Connection

Terminals of controller	C1 connector	Remark
Fuel relay output	5&8	
Start relay output	-	Connect to starter coil directly.

Table 24 – 3-Pin Connector Wiring Connection

Terminals of controller	3 pin data link connector		Re	emark		
CAN(H) (ECU)	A	Impedance	120Ω	connecting	line	is
		recommende	ed.			
CAN(L) (ECU)	В	Impedance	120Ω	connecting	line	is
		recommende	ed.			

Engine type: Cummins ISB



11.3.4 DETROIT DIESEL DDEC III / IV

Table 25 – Engine Wiring Connection

Terminals of controller	Engine CAN port		Re	mark		
	Expand 30A relay; battery					
Fuel relay output	voltage of ECU is supplied					
	by relay					
Start relay output	-	Connect to starter coil directly				
	CAN(U)	Impedance	120Ω	connecting	line	is
CAN(H) (ECU) CAN(H)		recommende	ed.			
	CAN(L)	Impedance	120Ω	connecting	line	is
		recommende	ed.			

Engine type: Common J1939

11.3.5 DEUTZ EMR2

Table 26 – Engine Wiring Connection

Terminals of controller	F connector	Remark
Fuel relay output	Expand 30A relay, battery voltage of terminal 14 is supplied by relay. Fuse is 16A.	
Start relay output	-	Connect to starter coil directly
-	1	Connect to battery negative.
CAN(H) (ECU)	12	Impedance 120Ω connecting line is recommended.
CAN(L) (ECU)	13	Impedance 120Ω connecting line is recommended.

Engine type: Volvo EDC4

11.3.6 JOHN DEERE

Table 27 – Engine Wiring Connection

Terminals of controller	21 pin connector		Re	mark		
Fuel relay output	G, J					
Start relay output	D					
		Impedance	120Ω	connecting	line	is
	V	recommended.				
		Impedance	120Ω	connecting	line	is
		recommende	ed.			

Engine type: John Deere



11.3.7 MTU MDEC

Compatible with MTU 2000 and 4000 series engines.

Terminals of controller	X1 connector	Remark
Fuel relay output	BE1	
Start relay output	BE9	
CAN(H)(ECU)	G	Impedance 120Ω connecting line is
		recommended.
CAN(L)(ECU)	F	Impedance 120Ω connecting line is
		recommended.

Engine type: MTU-MDEC-303

11.3.8 PERKINS

Compatible with ADEM3/ ADEM4 engine control modules. Engine types: 2306, 2506, 1106, and 2806.

Terminals of controller	Connector	Remark
Fuel relay output	1,10,15,33,34	
Start relay output	-	Connect to starter coil directly
CAN(H) (ECU)	31	Impedance 120Ω connecting line is
		recommended.
CAN(L) (ECU)	32	Impedance 120Ω connecting line is
		recommended.

Table 29 – Engine Wiring Connection

Engine type: Perkins

11.3.9 SCANIA

Compatible with S6 engine control module. Engines: DC9, DC12, DC16.

Table 30 – Engine Wiring Connection

Terminals of controller	B1 connector	Remark
Fuel relay output	3	
Start relay output	-	Connect to starter coil directly
CAN(H) (ECU)	9	Impedance 120Ω connecting line is
		recommended.
CAN(L) (ECU)	10	Impedance 120Ω connecting line is
		recommended.

Engine type: Scania



11.3.10 VOLVO EDC3

Compatible with such engines as TAD1240, TAD1241, and TAD1242.

Table 31 -	 Fuel Start 	Wiring	Connection
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Terminals of controller	"Stand alone" connector	Remark
Fuel relay output	Н	
Start relay output	E	
Auxiliary output 1	Р	Set auxiliary output 1 as "Preheating until cranking" and set preheating time as 5 seconds.

Table 32 – CANBUS Wiring Connection

Terminals of controller	"Data bus" connector	Remark				
CAN(H) (ECU)	1	Impedance	120Ω	connecting	line	is
		recommende	ed.			
CAN(L) (ECU)	2	Impedance	120Ω	connecting	line	is
		recommende	ed.			

Engine type: Volvo

11.3.11 VOLVO EDC4

Compatible engine types are TD520, TAD520 (optional), TD720, TAD720 (optional), TAD721, and TAD722.

Table 33 – Engine Wiring Connection

Terminals of controller	Connector	Remark
Fuel relay output	Expand 30A relay, battery voltage of terminal 14 is supplied by relay. Fuse is 16A.	
Start relay output	-	Connect to starter coil directly.
	1	Connect to battery negative.
CAN(H) (ECU)	12	Impedance 120Ω connecting line is
		recommended.
CAN(L) (ECU)	13	Impedance 120Ω connecting line is
		recommended.

Engine type: Volvo EDC4



en

11.3.12 VOLVO-EMS2

Compatible with the following Volvo engines: D9、D13、D16、EMS

Table 34 – Engine Wiring Connection

Terminals of controller	Engine CAN port	Remark	
	5	ECU power supply	
Auxiliary output 2		Set auxiliary output 2 as "ECU Power	
		Supply"	
CAN(H) (ECU)	1(CAN H)	Impedance 120Ω connecting line is	
		recommended.	
CAN(L) (ECU)	2(CAN L)	Impedance 120Ω connecting line is	
		recommended.	

Input ports can be set with speed control function, auxiliary input port 1 can be set as speed up input, and auxiliary input port 2 can be set as speed down input. After the normal running, raise/drop speed functions can be achieved by digital input ports.

Engine type: Volvo-EMS2

11.3.13 BOSCH

Compatible with BOSCH common rail electronic engines.

Table 35 – Engine Wiring Connection

Terminals of controller	42 pin engine port	Remark
	4 40	
Fuel relay output	1.40	Connect to engine ignition switch.
Start relay output	-	Connect to starter coil directly
CAN(H) (EXPANSION)	1.35	Impedance 120Ω connecting line is recommended.
CAN(L) (EXPANSION)	1.34	Impedance 120Ω connecting line is recommended.

 Table 36 – Power Wiring Conenction

Battery	2 pin engine port	Remark
Battery negative	1	Wire size: 2.5mm ²
Battery positive	2	Wire size: 2.5mm ²

Engine type: BOSCH

Please contact us if you have any questions about controller and ECU connection.



12 HMC4100 APPLICATION DIAGRAM



Fig.4 – HMC4100 Application Diagram

13 COMMISSIONING

Doing the following check before the system starting to run formally is recommended:

- Ensure all the connections are correct and wires diameter is suitable;
- Ensure that the controller DC power has fuse, controller's positive and negative connected to start battery are correct;
- Take proper action to prevent engine to crank success (e. g. Remove the connection wire of fuel valve). If checking is OK, make the start battery power on;
- Make the local mode active and then the controller enter into local mode. Press the Start button and the engine will start. If engine failed to fire, the genset will enter into ETS status automatically;
- Recover the action to prevent engine to crank success e. g. Connect wire of fuel valve), press start button again, and the engine will start. The engine will run from safety on delay to normal running if all works regularly. During this time, please watch the running status. If abnormal, stop engine and check all wires connection according to this manual.
- If there is any other question, please contact Smartgen's service.



14 INSTALLATION

14.1 FIXING CLIPS

Controller is panel built-in design; it is fixed by clips when installed.

- Withdraw the fixing clip screw (turn anticlockwise) until it reaches proper position.
- Pull the fixing clip backwards (towards the back of the module) ensuring two clips are inside their allotted slots.
- Turn the fixing clip screws clockwise until they are fixed on the panel.

A NOTE: Care should be taken not to over tighten the screws of fixing clips.

14.2 OVERALL DIMENSIONS AND CUTOUT DIMENSIONS



Fig.5 – Overall & Cutout Dimension

15 INSTALLATION ATTENTIONS

15.1 BATTERY VOLTAGE INPUT

HMC4100 controller can suit for widely range of battery voltage DC (8~35) V. Negative of battery must be connected with the engine shell. The diameter of wire which is from power supply to battery must be over 2.5mm². If floating charge configured, please firstly connect output wires of charger to battery's positive and negative directly, then, connect wires from battery's positive and negative input ports in order to prevent charge disturbing the controller's normal working.

15.2 SPEED SENSOR INPUT

Speed sensor is magnetic equipment which is installed on engine body for testing flywheel teeth number. 2 core shielding wire is used for the connection of the sensor and controller. The wire is supposed to be connected to 26 terminal of controller with one end and the other end hanging in the air. The other two signal lines connect separately to 28, 29 terminal. Speed sensor output voltage is supposed to be at AC (1-24) V (virtual value) when it is in full speed range, and AC12V (when in rated rotate speed) is recommened. When install the speed sensor, screw it to contact the flywheel firstly, inverse it with 1/3 circle, and then tighten the nut finally.



15.3 OUTPUT AND EXPANSION RELAY

All outputs of controller are relay contact output type. If expansion relays are needed, please add freewheel diode to both ends of expansion relay's coils (when coils of relay has DC current) or add resistance-capacitance return circuit (when coils of relay has AC current), in order to prevent charge disturbing the controller or others equipment.

15.4 WITHSTAND VOLTAGE TEST

When controller has been installed in control panel, if need the high voltage test, please disconnect controller's all terminals in order to prevent high voltage into controller and damage it.

16 TROBLESHOOTING

Problem	Possible Solution
Controller no response with power.	Check starting batteries; Check controller connection wirings; Check DC fuse.
Genset shutdown	Check the water/cylinder temperature is too high or not.
Emergency shutdown	Check emergency shutdown button function;
Low oil pressure alarm after engine has fired.	Check oil pressure sensor and wiring.
High water temperature alarm after engine has fired.	Check water temperature sensor and its wiring.
Shutdown alarm when engine	Check relevant switch and its wiring according to the information on LCD.
is running	Check auxiliary digital input port.
Fail to start	Check fuel return circuit and its wiring. Check starting battery. Check speed sensor and its wiring. Consult engine manual.
Starter no respond	Check starter wiring; Check start battery
RS485 communication failure	Check wiring; Check if COM port setting is right; Check if RS485 A and B wires are connected in the opposite way; Check if PC communication port is damaged.
CANBUS communication failure	Check wiring; Check if CANBUS CANH and CANL wires are connected in the opposite way; Check if CANBUS CANH and CANL wires at both ends are connected in the opposite way;
	Putting a 120Ω resistance between CANBUS CANH and CANL is recommended.

Table 38 – Trouble Shooting